UNITED STATES BANKRUPTCY COU	RT	
SOUTHERN DISTRICT OF NEW YORK		
	X	
	:	
In re	:	Chapter 11
DELPHI CORPORATION, et al.,		Case No. 05-44481 (RDD)
	:	
	:	(Jointly Administered)
Debtors.	:	
	X	

APPENDIXES A - J

TO

RESPONSE OF ROBERT BOSCH GmbH TO DEBTORS' THIRD OMNIBUS OBJECTION TO CLAIMS

APPENDIX A

Appendix A



General Specification

GMW - 3320 Epsilon

General Motors Baseline Component Technical Specification

SDM/ESS - 40.7.03

Version 3.5

April (8) 2000

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General Specification

GMW - 3320 Epsilon

Table 3.1.4.2.5-I Resistance of Deployment Loops

PARAMETER	MIN.	MAX.	UNITS
Initiator Resistance	1.7	2.3	Ω
0.5 Ohm Clock spring Coil Resistance(both legs)(T _c = .00385		A CONTRACTOR OF THE CONTRACTOR	m = milli
ohms/ohm/°C @ 25°C)			
$T_a = 25^{\circ}C$	300	600	$\mathbf{m}\Omega$
$T_a = -40$ °C to 85°C	236.5	738.6	mΩ
Wire resistance for any deployment loop 1.83 to 9.14 m (6-30) of SAE^1 0.35 mm ² wire @51.5 mohms/m (bare wire w/o tin coating) with T_c =.00385 ohms/ohm/°C @25°C	1.83	9.14	meters
$T_a = 25^{\circ}C$	94.3	470.8	mΩ
$T_a = -40^{\circ}\text{C to } 85^{\circ}\text{C}$	74.3	579.6	$\mathbf{m}\Omega$
Connector Interfaces:	1 3		
(Driver stage 1 and 2 airbag has 6 connections @ .02 (Preach)		120.0	$m\Omega$
(Passenger stage 1 and 2 airbag has up to 6 connections 10.02 Ω	T 0.0	120.0	$m\Omega$
each)	0.0	160.0	$\mathbf{m}\Omega$
(Front and Rear Side and Overhead Impact Arbag has up to 8 connections @ .02 Ω each) (Each pretensioner has up to 8 connections @ .02 Ohm each)	0.0	160.0	mΩ
	1		
Increase in initiator resistance during deployment	0.0	0.5	Ω
Total Diagnostic Resistance (for including initiator resistance increase)			
Driver Loop (@27C/@Temp. Limits)	2,09/2.01	3.49/3.74	Ω
Pretensioner (@25 C/@ Temp. Limits)	1.79/1.77	2.93/3.04	
Total deploy loop resistance (including initiator resistance increase)	200001	0.0044.04	-
Driver Loop (@25°C /@Temp. Limits)	2.09/2.01	3.99/4.24	Ω
Pretensioner (@25 C /@ Temp. Limits)	1.79/1.77	3.43/3.54	

3.1.4.2.5.2 Deployment Loop Assignments

- Loops 1-4 shall be dedicated to frontal airbags.
- b. To minimize permutations, odd numbered loops shall be restricted to the driver side and even numbered loops to the passenger side.
- c. Other loop assignments shall be directed by the platform.
- Energy reserve shall be assigned to loops 1-4.
- e. Assignments shall be configurable at the vehicle assembly plant through a CLASS 2/GMLAN message or at the supplier's facility which will be jointly determined by GM and the supplier.

¹ Note: A similar calculation is required for SAE 0.5 mm² wire gage.

Appendix A, Page 17



General Specification

GMW – 3320 Epsilon

The SDM shall provide redundant power for deployment using vehicle electrical power and the reserve (where mechanized).

3.2.1.4.1 Deployment Energy Reserve

The requirements for the SDM energy reserve are:

- a. The SDM shall provide an energy reserve for the first 4 deployment loops to allow deployment 150 ms after power to the battery input is lost. This shall apply to each frontal airbag, including both levels if dual level frontal airbags are implemented.
- b. The specified energy reserve times shall be provided for voltages between 9.0 and 16.0 volts inclusive using the worst-case deployment loop resistance.
- c. A shorted ignition input shall not deplete the energy reserves prior to commanded deployment.
- d. A shorted squib or short to ground in one or more deployment loops (e.g., shorted squib caused by a plasma forming in the igniter) shall not result in the inability to deploy other deployment loops or cause the energy reserve times in the other loops to be less than 150 ms.
- e. If the SDM has detected a frontal crash event is in progress as specified in 3.2.2 Physical Characteristics, the SDM shall not resettany SDM function when electrical power disruptions of any length up to 150 ms occur.
- f. Energy reserve capacitors for the second pair of loops shall be individually 'parts deletable' at platform direction.

3.2.1.4.2 EFS Energy Reserve

- a. The supplier shall package protect an area of the printed circuit board so that a 'parts deletable' common energy reserve can be included as specified by individual platforms.
- b. When an energy reserve is provided for the EFS (see 32.1.4.2) and battery voltage drops below 9 volts, each of the two EFSs shall operate without interruption for a minimum of 60 msec.
- c. The reserve time shall be a minimum of 60 ms under the assumption that neither EFS is shorted during impact. Under shorted conditions (for either or both EFS), the EFS reserve shall be a minimum of 50 msec.
- d. The specified energy reserve times shall be provided when battery voltage is between 9.0 and 16.0 volts.
- A short to ground on both EFS devices shall not degrade the 150 ms energy reserve time USED FOR SINGLE POINT SENSING.
- A shorted battery input to the SDM shall not deplete the energy reserve prior to commanded deployment.

3.2.1.4.3 Other Energy Reserves

See appropriate appendix.

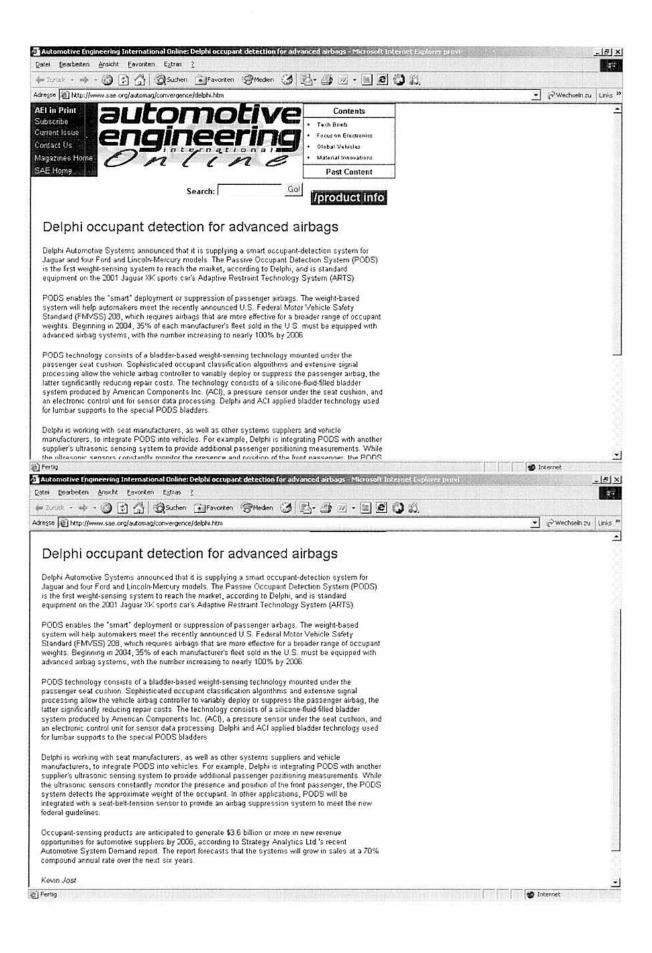
3.2.1.5 Perform Under Specific Environments

Several specific environmental conditions for which an associated SDM/ESS performance is required are defined in the following paragraphs.

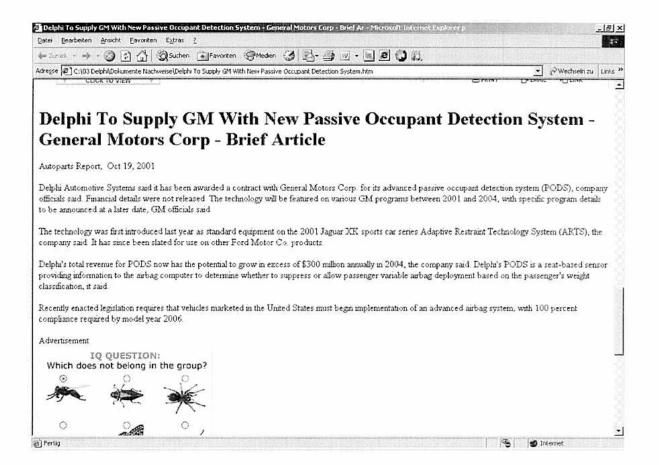
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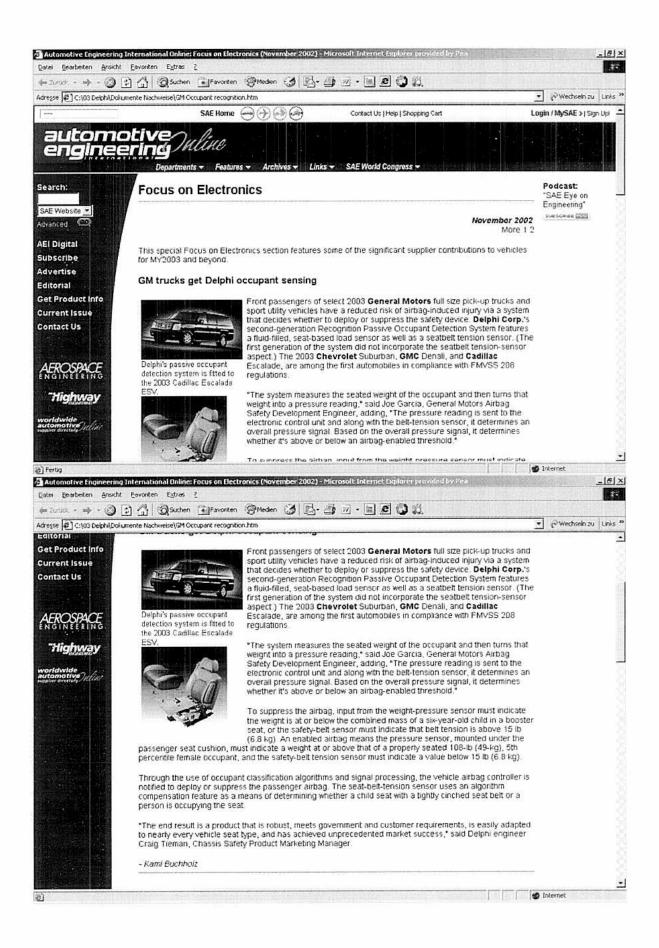
APPENDIX B



APPENDIX C



APPENDIX D



APPENDIX E



SAFETY & SECURITY SYSTEMS

Delphi Passive Occupant Detection System B

Description

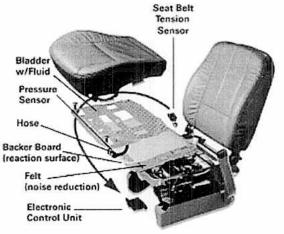
The Delphi Passive Occupant Detection System (PODS-B) is designed to classify the occupant seated in the front passenger seat for potential airbag suppression. It consists of a pressure sensor, bladder assembly, belt tension sensor and an electronics control unit (ECU). The sensing system detects loading force on the front passenger seat and classifies the seat as empty or the occupant as an adult or infant/child. The ECU processes the sensor data and provides a deployment-allowed output to the vehicle's sensing and diagnostic module when a defined threshold is met.

Benefits

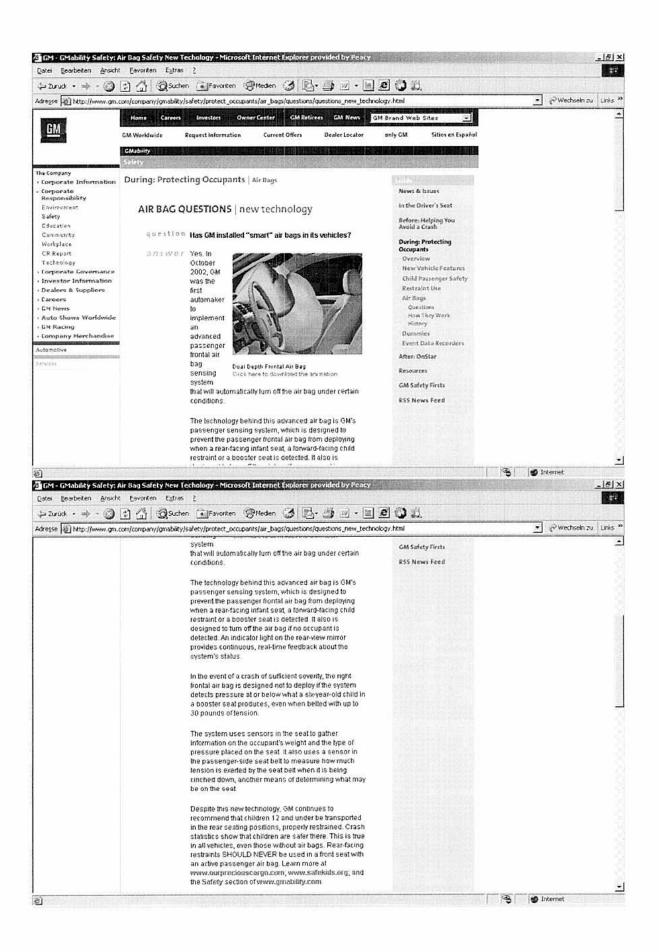
- Helps reduce the potential for airbag-induced injury
 - Allows airbag suppression when seat is empty
 - Allows airbag suppression when occupant is below defined threshold
 - Allows airbag suppression for children as defined by the advanced airbag regulation FMVSS 208
 - Allows airbag deployment when 5th percentile female and larger adults are present
 - Does not require driver action to suppress passenger airbag
- Integrated into the seat assembly
- · Uses low-cost, proven automotive technologies

Features

- Differentiation of cinched vs. uncinched seat occupants using dynamic pressure information and vertical acceleration
- · Calibratable thresholds
- Accepts input from a belt tension sensor for FMVSS 208 compliance
- Interfaces with sensing and diagnostic modules equipped with an airbag suppression feature



APPENDIX F



APPENDIX G



APPENDIX H

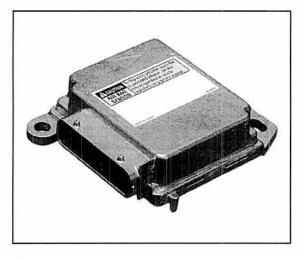
Safety and Security

Diagnostic Sensing n d SDM-GF

Description - The SDM-GF Sensing and Diagnostic Module (SDM) is the safety restraint system central control module and is designed to provide sensing and discrimination of crash pulses and control of deployable restraints. The SDM is designed for installation within the vehicle passenger compartment and will sense crashes independently (frontal only) or in conjunction with frontal and side satellite crash sensors. The SDM is also designed to automatically allow or suppress passenger airbag deployment based upon inputs from either a manual airbag deactivation switch or an automatic occupant sensor. It contains crash data recording capability and provides a serial data link for vehicle systems communication.

Features

- Algo-SSM severity-based algorithm with pretensioner, single or dual-stage airbag deployment capability
- Frontal crash discrimination
- Support of 2 frontal and 2 side satellite sensors
- Frontal and side impact logic-level safing
- 1-12 pyrotechnic loop capability (configurable)
- Supports automatic occupant sensor input for passenger airbag suppression to meet new FMVSS208 regulations
- Diagnostics of driver and passenger seatbeltbuckled and seat position switches
- Class 2 (SAE J-1850) vehicle bus to enhance vehicle communications capability
- Crash data recording functions to assist forensic engineering
- Energy reserves on specific airbag loops and frontal satellite sensors for crashes with battery disconnects
- Water-resistant package and connector system
- Unique mechanical connector is keyed for each vehicle calibration to help ensure proper vehicle application



Consumer Benefits

- Designed to protect front seat passengers in frontal crashes by deploying single or dual-stage frontal airbags and pretensioners
- Designed to protect front and rear seat passengers in side crashes by deploying thorax airbags
- Capable of disabling deployment of passenger airbags through the use of an automatic occupant sensor input

OEM Benefits

- Provides necessary functions to support a FMVSS208-compliant safety restraint system
- Provides many vehicle configuration and calibration options to enable tailoring system performance to unique vehicle requirements



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APPENDIX I

Crash Sensing Capability

Proven Experience

- Secure crash library containing 5,000+ crash events and 20,000+ abuse/rough road events
- Production central controllers since 1989 and electronic satellite sensors since 1997
- Extensive experience on sensor location optimization on a wide range of platforms – from small cars to trucks

Innovative Algorithms

- Acceleration-based measures for either single-point or multi-point systems
- Sophisticated deployment logic allows flexibility for single or multi-stage airbags
- Separate arming/safing functions increase system fault tolerance for multisensor system
- Acceleration / Pressure satellite sensors provide optimized sensing system

Unique Sensing Solutions

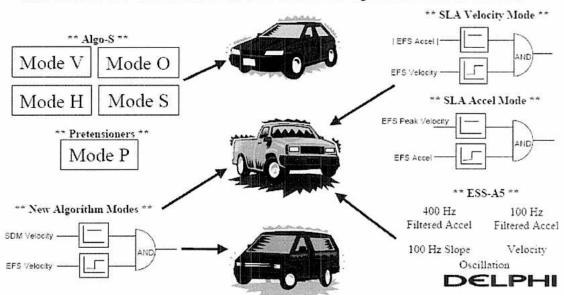
- Single or multi-point systems for both single and dual stage frontal airbags
- Capable of both pillar and door sensor location for side airbags



DELPHI

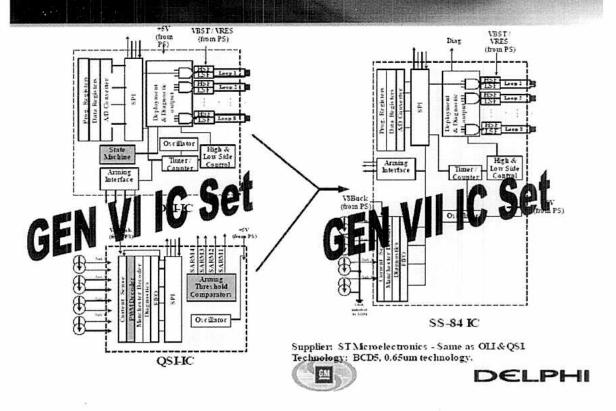


Each algorithm module shall be optimized and identified with Critical Computer Resources (CCR), then each vehicle application shall be given a CCR "budget" that must not be exceeded for the sum total of all algorithm modules chosen.



APPENDIX J

SS-84 Building Block Architecture



Squib & Satellite Interface IC SS-84, SS-42

Deployment loop interface functions

- 1.2 amp, 2.0 msec minimum deployment current levels
- SPI deployment communications
- Independent deployment enable (DEPEN) input
- Independently controlled high-side and low-side FETs
- Independent SPI arming input with pulse stretch
- Analog output for resistance measurement diagnostics
- Short to battery, short to ground and open loop detection
- Deployment Driver Test
 - » Hardware controlled turn off of FET test
 - » Continuous short to battery and ground check with disable
 - » Continuous differential voltage check with disable
- Loss of ground connection diagnostic

